

# Generating Functions for Canonical Transformations

• We want to construct a canonical transformation such that

$$Q_i = Q_i(q_j, p_j, t), \quad P_i = P_i(q_j, p_j, t), \quad K = K(Q_j, P_j, t)$$

↑  
Hamiltonian in  
new coordinates

with

$$\dot{Q}_j = \frac{\partial K}{\partial P_j}, \quad \dot{P}_j = -\frac{\partial K}{\partial Q_j}$$

(and  $\{Q_j, P_k\} = \delta_{jk}, \{Q_j, Q_k\} = \{P_j, P_k\} = 0$ )

Hamilton's eqs. can be derived from the variational principle

$$\delta \int_{t_1}^{t_2} \left( \sum_k P_k \dot{Q}_k - H(q_j, p_j, t) \right) dt = 0$$

which should be invariant under the canonical transformation as well, so we must also have (up to a total time derivative),

$$\delta \int_{t_1}^{t_2} \left( \sum_k P_k \dot{Q}_k - K(Q_j, P_j, t) \right) dt = 0$$

$$\Rightarrow \sum_k P_k \dot{Q}_k - H(q_j, p_j, t) = \sum_k P_k \dot{Q}_k - K(Q_j, P_j, t) + \frac{d\Phi}{dt}$$

$$\Leftrightarrow \boxed{\sum_k (P_k dq_k - P_k dQ_k) + (K - H) dt = d\Phi} \quad (*)$$

Also defines a canonical transformation. Eq. (\*) suggests that we view  $\Phi$  as a function of the old and new generalized coordinates.

Suppose we can solve

$$Q_i = Q_i(q_j, p_j, t) \rightarrow P_i(q_j, Q_j, t) \quad (**)$$

$$\hookrightarrow P_i = P_i(q_j, P_j(q_j, Q_j, t), t)$$

$\Rightarrow (q_j, Q_j, t)$  are independent variables. Define

$$F_1 \equiv \mathcal{F}(q_j, p_j(q_j, Q_j, t), t) = F_1(q_j, Q_j, t)$$

$$\Rightarrow dF_1 = \sum_k \left( \frac{\partial F_1}{\partial q_k} dq_k + \frac{\partial F_1}{\partial Q_k} dQ_k \right) + \frac{\partial F_1}{\partial t} dt$$

$$\stackrel{(*)}{=} \sum_k (p_k dq_k - P_k dQ_k) + (K - H) dt$$

$$\Rightarrow \left[ p_j = \frac{\partial F_1}{\partial q_j}, \quad P_j = - \frac{\partial F_1}{\partial Q_j}, \quad K(Q_j, p_j, t) = H(q_j(Q_j, p_j, t), p_j(Q_j, p_j, t), t) + \frac{\partial F_1}{\partial t} \right]$$

We assumed in Eq. (\*\*\*) and the discussion that we can solve for  $p_j(q_j, Q_j, t)$ , but what if that is inconvenient or impossible, e.g., for the identity transformation

$$Q_j = q_j, \quad P_j = p_j \quad ?$$

$\Rightarrow$  Take  $(q_j, P_j, t)$  (or  $(Q_j, p_j, t)$ ) as independent vars!

Express second term of Eq. (\*) as

$$- \sum_k P_k dQ_k = - d \left( \sum_k P_k Q_k \right) + \sum_k Q_k dP_k$$

to obtain

$$\sum_k (p_k dq_k + Q_k dP_k) + (K - H) dt = d \left( \sum_k P_k Q_k + \mathcal{F} \right)$$

$$\Rightarrow F_2(q_j, P_j, t) \equiv \sum_k P_k Q_k(q_j, P_j, t) + \underbrace{\mathcal{F}(q_j, p_j(q_j, P_j, t), t)}_{\approx \tilde{F}_1(q_j, P_j, t)} \quad \begin{array}{l} \text{Legendre} \\ \text{Trick!} \end{array}$$

$$\Rightarrow p_j = \frac{\partial F_2}{\partial q_j}, \quad Q_j = + \frac{\partial F_2}{\partial P_j}, \quad K(Q_j, P_j, t) = H(q_j, P_j, t) + \frac{\partial F_2}{\partial t}$$

We can find four basic types of canonical transformations via Legendre transforms:

$$F_1 = \tilde{\Phi}(q_j, Q_j, t), \quad p_j = \frac{\partial F_1}{\partial q_j}, \quad P_j = -\frac{\partial F_1}{\partial Q_j}, \quad K = H + \frac{\partial F_1}{\partial t}$$

$$F_2 = \sum_k p_k Q_k + \tilde{\tilde{\Phi}}(q_j, P_j, t), \quad p_j = \frac{\partial F_2}{\partial q_j}, \quad Q_j = \frac{\partial F_2}{\partial P_j}, \quad K = H + \frac{\partial F_2}{\partial t}$$

$$F_3 = -\sum_k q_k P_k + \tilde{\tilde{\Phi}}(P_j, Q_j, t), \quad q_j = -\frac{\partial F_3}{\partial P_j}, \quad P_j = -\frac{\partial F_3}{\partial Q_j}, \quad K = H + \frac{\partial F_3}{\partial t}$$

$$F_4 = -\sum_k (q_k p_k - Q_k P_k) + \tilde{\tilde{\Phi}}(P_j, P_j, t), \quad q_j = -\frac{\partial F_4}{\partial P_j}, \quad Q_j = \frac{\partial F_4}{\partial P_j}, \quad K = H + \frac{\partial F_4}{\partial t}$$

Can mix  $F_1, F_2, F_3, F_4$  for pairs of canonical vars  $(q, p) \rightarrow (Q, P)$   
 (e.g. transform  $(q_1, p_1)$  according to  $F_1$ ,  $(q_2, p_2)$  according to  $F_2, \dots$ )

Examples : i) Application of generating functions

$$F_2(q_i, P_i, t) \equiv \sum_{k=1}^n q_k P_k$$

We have

$$p_j = \frac{\partial F_2}{\partial q_j} = P_j, \quad Q_j = \frac{\partial F_2}{\partial P_j} = q_j$$

which is just the identity.

ii)

$$F_1(q_i, Q_i, t) \equiv \sum_{k=1}^n q_k Q_k$$

$$p_j = \frac{\partial F_1}{\partial q_j} = Q_j, \quad P_j = -\frac{\partial F_1}{\partial Q_j} = -q_j$$

↳ Up to a sign, this is an interchange of coordinates and momenta.